Probability

Dicrete Random Variables

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Introduction to probability theory

Real Random Variable

Discrete Random Variables

Moments of a discrete random variable

Two Random Variables

Introduction to probability theory









Randomness (Uncertainty)

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 $\Omega = \{1, 2, 3, 4, 5, 6\}$

finite countable

set



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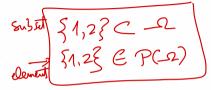
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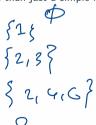
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$$P(-2) = \{\phi, 3n\}, \frac{1}{52}, \frac{1}{53}, \frac{1}{52}, \frac{1}{53}, \frac{1}{53$$





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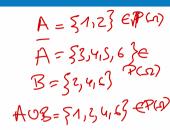


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- **•** σ-Algebra: We call σ-Algebra any family \mathcal{A} of subsets of Ω satisfying:

$$\begin{cases} 1. & \Omega \in \mathcal{A}. \\ 2. & \text{if } \overline{A \in \mathcal{A}}, \text{ then } \overline{A} \in \mathcal{A}. \\ 3. & \text{if } (A_n)_{n \in \mathbb{N}} \text{ is a sequence of elements in } \mathcal{A}, \text{ then } \bigcup_{n \in \mathbb{N}} A_n \in \mathcal{A}. \end{cases}$$



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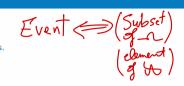
1.
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.
2. if $A \in \mathcal{A}$, then $\overline{A} \in \mathcal{A}$.
3. if $(A_n)_{n \in \mathbb{N}}$ is a sequence of elements in \mathcal{A} , then $\bigcup_{n \in \mathbb{N}} A_n \in \mathcal{A}$.
 (Ω, \mathcal{A}) is a measurable space (or a Borel space).



Notions on Events

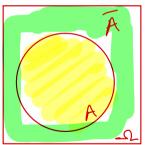
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- ▶ Operations on events. Let A and B be two events:
 - \overline{A} is the complement event of A (we also note A^c). $\underline{barA=Om \setminus A}$. \underline{barA} occurs if and only if A does not occur.
 - A∩B is the event «A and B».
 A∩B occurs when both events occur.
 - $A \cup B$ is the event «A or B». $A \cup B$ occurs when at least one of the two events occurs.



A-JLA



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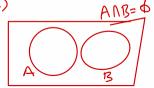
• $A \cap B$ is the event «A and B». A \cap B occurs when both events occur.

A=)B

- $A \cup B$ is the event «A or B». A \cup B occurs when at least one of the two events occurs.
- Mutually Exclusive Events: A and B are mutually exclusive if their simultaneous realization is impossible: $A \cap B = \emptyset$. \forall in compatible events (disjoint events)

A

▶ Implication: A implies B means that if A occurs, then B also occurs: $A \subset B$.

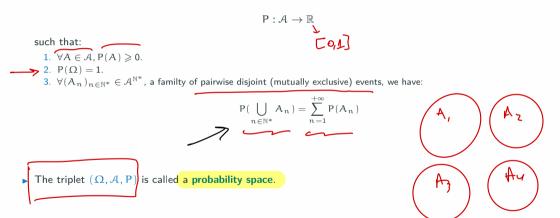


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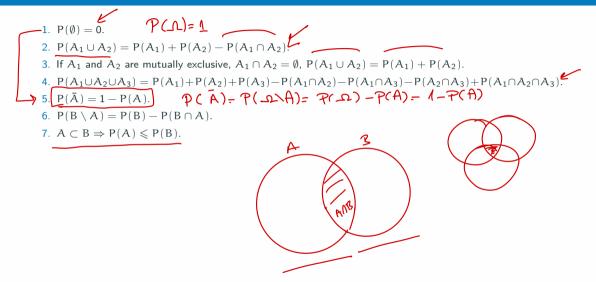
Probability Space

▶ Let (Ω, A) a measurable space. A probability function on (Ω, A) , is any map





Probability: Properties





- **1**. $P(\emptyset) = 0$.
- 2. $P(A_1 \cup A_2) = P(A_1) + P(A_2) P(A_1 \cap A_2)$.
- 3. If A_1 and A_2 are mutually exclusive, $A_1 \cap A_2 = \emptyset$, $P(A_1 \cup A_2) = P(A_1) + P(A_2)$.
- 4. $P(A_1 \cup A_2 \cup A_3) = P(A_1) + P(A_2) + P(A_3) P(A_1 \cap A_2) P(A_1 \cap A_3) P(A_2 \cap A_3) + P(A_1 \cap A_2 \cap A_3).$
- 5. $P(\bar{A}) = 1 P(A)$.
- 6. $P(B \setminus A) = P(B) P(B \cap A)$.

molonm

7. $A \subset B \Rightarrow P(A) \leq P(B)$.

Uniform probability on finite Ω

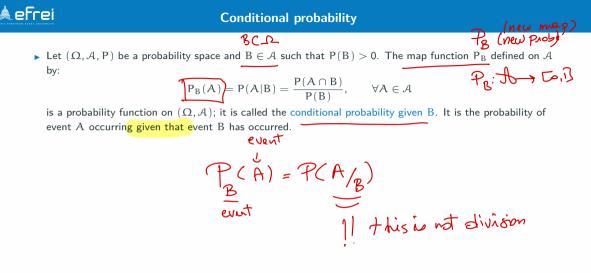
Jair die Aievent: "even nd" =) Uniform P A= § 2,4,6} P(A) - IAI = 1 = 6 = 2 Let Ω be a finite sample space. We say that P is the uniform probability on the measurable space $(\Omega, P(\Omega))$ if:

$$\forall \omega, \omega' \in \Omega, \qquad \mathsf{P}(\omega') = \mathsf{P}(\omega')$$

 $\forall A \in \mathcal{A}, \quad P(A) = \frac{Card(A)}{Card(\Omega)} = /A$

One also says that there is **equiprobability** of elementary events.

▶ Let $(\Omega, \mathcal{P}(\Omega), P)$ be a finite probability space. If P is the uniform probability, then





$$P_B(A) = P(A|B) = \frac{P(A \cap B)}{P(B)}, \quad \forall A \in A$$

is a probability function on (Ω, A) ; it is called the conditional probability given B. It is the probability of event A occurring given that event B has occurred.

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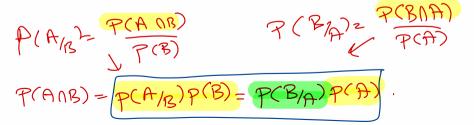


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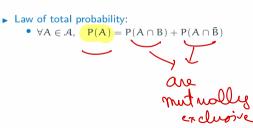


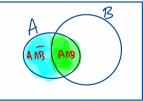
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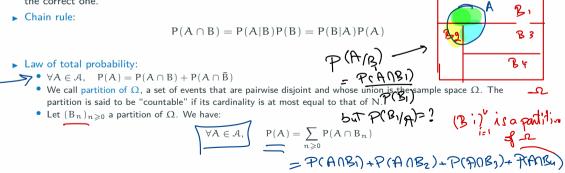




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• Let (Ω, \mathcal{A}, P) be a probability space and $B \in \mathcal{A}$ such that P(B) > 0. The map function P_B defined on \mathcal{A} by: $P_B(A) = P(A|B) = \underbrace{\overbrace{P(A \cap B)}^{P(A \cap B)}}_{P(B)}, \quad \forall A \in \mathcal{A} \qquad \Leftrightarrow \begin{array}{c} A + B \text{ are border} \\ P(A|B) = P(A|B) = \underbrace{P(A \cap B)}_{P(B)}, \quad \forall A \in \mathcal{A} \qquad \Leftrightarrow \begin{array}{c} A + B \text{ are border} \\ P(A|B) = P(A|B) = \underbrace{P(A \cap B)}_{P(B)}, \quad \forall A \in \mathcal{A} \qquad \Leftrightarrow \begin{array}{c} A + B \text{ are border} \\ P(A|B) = P(A|B) = \underbrace{P(A \cap B)}_{P(B)}, \quad \forall A \in \mathcal{A} \qquad \Leftrightarrow \begin{array}{c} A + B \text{ are border} \\ P(A|B) = P(A|B) = \underbrace{P(A \cap B)}_{P(B)}, \quad \forall A \in \mathcal{A} \qquad \Leftrightarrow \begin{array}{c} A + B \text{ are border} \\ P(A|B) = P(A|B) = \underbrace{P(A \cap B)}_{P(B)}, \quad \forall A \in \mathcal{A} \qquad \Leftrightarrow \begin{array}{c} A + B \text{ are border} \\ P(A|B) = P(A|B) = \underbrace{P(A \cap B)}_{P(B)}, \quad \forall A \in \mathcal{A} \qquad \Leftrightarrow \begin{array}{c} A + B \text{ are border} \\ P(A|B) = P(A|B) = \underbrace{P(A \cap B)}_{P(B)}, \quad \forall A \in \mathcal{A} \qquad \Leftrightarrow \begin{array}{c} A + B \text{ are border} \\ P(A|B) = P(A|B) = \underbrace{P(A \cap B)}_{P(B)}, \quad \forall A \in \mathcal{A} \qquad \Leftrightarrow \begin{array}{c} A + B \text{ are border} \\ P(A|B) = P(A|B) = \underbrace{P(A \cap B)}_{P(B)}, \quad \forall A \in \mathcal{A} \qquad \Leftrightarrow \begin{array}{c} A + B \text{ are border} \\ P(A|B) = P(A|B) = \underbrace{P(A \cap B)}_{P(B)}, \quad \forall A \in \mathcal{A} \qquad \bigoplus \begin{array}{c} A + B \text{ are border} \\ P(A|B) = P(A|B) = \underbrace{P(A \cap B)}_{P(B)}, \quad \forall A \in \mathcal{A} \qquad \bigoplus \begin{array}{c} A + B \text{ are border} \\ P(A|B) = P(A|B) = \underbrace{P(A \cap B)}_{P(B)}, \quad \forall A \in \mathcal{A} \qquad \bigoplus \begin{array}{c} A + B \text{ are border} \\ P(A|B) = P(A|B) = \underbrace{P(A \cap B)}_{P(B)}, \quad \forall A \in \mathcal{A} \qquad \bigoplus \begin{array}{c} A + B \text{ are border} \\ P(A|B) = P(A|B) = \underbrace{P(A \cap B)}_{P(B)}, \quad \forall A \in \mathcal{A} \qquad \bigoplus \begin{array}{c} A + B \text{ are border} \\ P(A|B) = P(A|B) = \underbrace{P(A \cap B)}_{P(B)}, \quad \forall A \in \mathcal{A} \qquad \bigoplus \begin{array}{c} A + B \text{ are border} \\ P(A|B) = P(A|B) = \underbrace{P(A|B)}_{P(B)}, \quad \forall A \in \mathcal{A} \qquad \bigoplus \begin{array}{c} A + B \text{ are border} \\ P(A|B) = P(A|B) = \underbrace{P(A|B)}_{P(B)}, \quad \forall A \in \mathcal{A} \qquad \bigoplus \begin{array}{c} A + B \text{ are border} \\ P(A|B) = P(A|B) = \underbrace{P(A|B)}_{P(B)}, \quad \forall A \in \mathcal{A} \qquad \bigoplus \begin{array}{c} A + B \text{ are border} \\ P(A|B) = P(A|B) = \underbrace{P(A|B)}_{P(A|B)}, \quad \forall A \in \mathcal{A} \ \emptyset \end{array} \right)$

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- ► Law of total probability:
 - $\forall A \in \mathcal{A}, P(A) = P(A \cap B) + P(A \cap \overline{B})$
 - We call partition of Ω, a set of events that are pairwise disjoint and whose union is the sample space Ω. The
 partition is said to be "countable" if its cardinality is at most equal to that of N.
 - Let $(B_n)_{n \ge 0}$ a partition of Ω . We have:

$$\forall A \in \mathcal{A}, \qquad P(A) = \sum_{n \ge 0} P(A \cap B_n) \quad \longleftarrow \quad \mathsf{Independence: Events } A \text{ and } B \text{ are independent iff } P(A \cap B) = P(A)P(B). \quad (\mathcal{B} \land \mathcal{A}) = \mathcal{P}(\mathcal{B}))$$

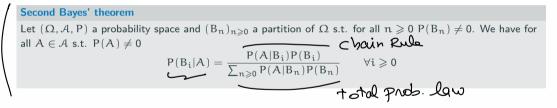


Bayes' formulae

First Bayes' theorem

Let (Ω, \mathcal{A}, P) a probability space. For all events A and B such that $P(A) \neq 0$ and $P(B) \neq 0$, we have:

$$P(B|A) = \frac{P(A|B)P(B)}{P(A)}$$



Break Real Random Variable

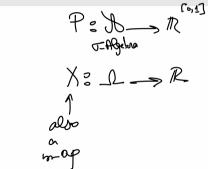




Concept of Real Random Variable

Definition

Let ε an experiment and (Ω, \mathcal{A}, P) the associated probability space. In many situations, one associates to each result $\omega \in \Omega$ a real number denoted $\underline{X}(\omega)$; In this way, one builds a map $X : \Omega \to \mathbb{R}$. Historically, ε was a game and X représented the earning of a player.





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Example: a die throw

A player throws a fair six faces dice and we observe the obtained number:

- ▶ If the result is 1,3 or 5, the player earns 1 euro.
- ▶ If the result is 2 or 4, the player earns 5 euros.
- ▶ If the result is 6, the player loses 10 euros.



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▶ P is the equiprobability on (Ω, \mathcal{A}) . $(-\Lambda, \mathcal{P}, \mathcal{P})$ is the probability space



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So we have

$$\begin{array}{c} \overbrace{X(1)}=\overbrace{X(3)}=\overbrace{X(5)}=1 \quad (+\pounds \notin) \\ \overbrace{X(2)}=X(4)=5 \quad (+ \not) \\ \overbrace{X(6)}=-10 \quad (- \land) \not \in) \end{array}$$
We say that X is a random variable on Ω .





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 $\{X = 1\}$



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P(X=1) = P(" obtain 101305") $= 1/2. = P(\le 1/3, S_{1}) = \frac{/31.3531}{(-2)}$ $= \frac{-3}{6} = 1/2.$ $\{X=1\}=\{\omega\in\Omega/X(\omega)=1\}=\{\omega\in\Omega/X(\omega)\in\{1\}\}=X^{-1}(\{1\})=\{1,3,5\}.$



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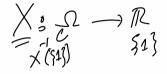
Similarly, we have:

▶ P(X = 5) = 1/3.



 $\Rightarrow X(\omega) = 1.$

- this is the case if and only if $\omega \in \mathfrak{M}3, 5$.
- The sought-for probability is therefore $P(\{1, 3, 5\}) = 1/2$.
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P(X=1)

Thus, we will consider the event:

$$(\{X = 1\}) = \{ \omega \in \Omega / X(\omega) = 1\} = \{ \omega \in \Omega / X(\omega) \in \{1\}\} = X^{-1}(0) \xrightarrow{\mathcal{O}} (1, 3, 5\}.$$

Similarly, we have:

- ▶ P(X = 5) = 1/3.
- ▶ P(X = -10) = 1/6.







xi	-10	1	5



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$p_i = P(X = x_i)$			
$\bigcirc \sim$			



xi	-10	1	5]
$p_i = P(X = x_i)$	1/6	1/2	1/3	
	1/2	3/2	2/6	- 1



xi	-10	1	5
$p_i = P(X = x_i)$	1/6	1/2	1/3

This is tantamount of considering a new sample space:

$$\begin{array}{c} \Omega_{X} = X(\Omega) \end{array} = \{-10, 1, 5\} \quad \text{possibilities of } X \\ \end{array}$$



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$$\mathsf{P}(\bigcup_{x_{\mathfrak{i}}\in\Omega_{X}}\{X=x_{\mathfrak{i}}\})=\sum_{x_{\mathfrak{i}}\in\Omega_{X}}\mathsf{P}(X=x_{\mathfrak{i}})=1$$



In this chapter:

- We treat the case where $X(\Omega)$ is countable.
- The random variable in this case is discrete.
- ▶ We define its probability law by its probability distribution.
- ▶ We will define the two main numerical characteristics of a discrete random variable:
 - Expected value: characteristic of centrality (the *mean*).
 - Variance: characteristic of dispersion.
- ▶ We will also define the couples of random variables.

Discrete Random Variables



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• The set $X(\Omega)$ of all possible values of X, sorted in ascending order: $X(\Omega) = \{x_1, x_2, \dots, x_i, \dots\}$ with $x_1 \leq x_2 \leq \dots \leq x_i \leq \dots$



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Remarks:

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$$\blacktriangleright P(a < X \leq b) = \sum_{i/a < x_i \leq b} p(x_i).$$

•
$$p(x_i) \ge 0$$
 and $\sum_{i=1}^{\infty} p(x_i) = 1$.

$$P(X \in T_{01}G) = P(X=1) + P(X=5)$$
in the prev.
$$= 1_{2} + 1_{2}$$

▶ If the number of possible values of X is small enough, the probability distribution of X is often presented as a table.



Given a discrete random variable X, we call cumulative distribution function of X (or simply distribution function), denoted F_X , the function defined by: for any real a, $F_X \ \stackrel{\circ}{\to} \ \stackrel{\circ}{\longrightarrow} \ \stackrel{\circ}$

$$a \in \mathbb{R}, \qquad F(a) = \frac{P(X \leq a)}{n} = \sum_{i/x_i \leq a} P(X = x_i)$$

The value $F_X(a)$ represents the probability that X takes a value smaller or equal to a.

$$F_{\chi}(a) = P(X \le a) \qquad \begin{array}{l} X = -Q \rightarrow R \\ F_{\chi}(a) = P(X \le a) & F_{\chi} = \frac{P(X \le a)}{F_{\chi}(2)} = P(X \le a) = P(X = -10) \\ F_{\chi}(x \le a) = P(X \le a) = P(X = -10) + P(X = 1) \\ \end{array}$$

Por Jan



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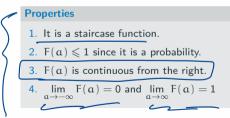
- 1. It is a staircase function.
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- 3. F(a) is continuous from the right.



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Properties

- 1. It is a staircase function.
- 2. $F(\alpha) \leq 1$ since it is a probability.
- 3. F(a) is continuous from the right.

4.
$$\lim_{a \to -\infty} F(a) = 0$$
 and $\lim_{a \to \infty} F(a) = 1$

The distribution function characterizes the distribution of X. In other words, if X and Y are two random variables, we have $F_X = F_Y$ if and only if their probability distributions are the same.



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This is easier to understand if one writes the event $\{X \leq b\}$ as a union of two incompatible events $\{X \leq a\}$ and $\{a < X \leq b\}$, Let

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In this way,

$$P(X \leq b) = P(X \leq a) + P(a < X \leq b)$$

which proves the equality above.



Distribution function and probabilities over X

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which proves the equality above.

Remark

One can compute the individual probabilities by:

$$p_i = P(X = x_i) = F(x_i) - F(x_{i-1}) \qquad \text{pour } 1 \leqslant i \leqslant n$$



We play three times to "heads or tails"



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•	Ω	=	{F	Р,	F	}3	•



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• Let's calculate P(X = 1).





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- $X^{-1}(1) = \{(P, F, F), (F, P, F), (F, F, P)\}.$



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 \Rightarrow P(X = 1) = $\frac{3}{8}$

Using the same method we obtain the probability distribution of X:

k	0	1	2	3	
P(X = k)	1/8	3/8	3/8	1/8)
					/



The distribution function X is therefore given by:

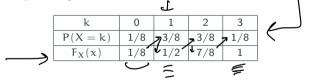
$$F(x) = \begin{cases} 0 & \text{si } x < 0\\ 1/8 & \text{si } 0 \leqslant x < 1\\ 1/2 & \text{si } 1 \leqslant x < 2\\ 7/8 & \text{si } 2 \leqslant x < 3\\ 1 & \text{si } x \geqslant 3 \end{cases}$$



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One can represent both the probability distribution and the distribution function of X in the same table:





The graph of the distribution function is represented below:

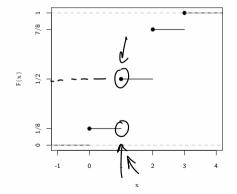




Figure 1: Distribution function



Here is another slightly different representation of the distribution function:

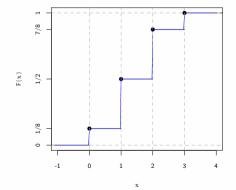


Figure 2: Distribution function



Let A an event. We call indicator random variable of the event A, the random variable $X = \mathbb{1}_A$ defined by:

$$X(\omega) = \begin{cases} 1 & si \ \omega \in A \\ 0 & si \ \omega \in \bar{A} \end{cases}$$



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ight.$$

Therefore:

▶
$$P(X = 1) = P(A) = p$$

•
$$P(X = 0) = P(\bar{A}) = 1 - p$$



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The distribution function of the indicator random variable is therefore:

$$\mathsf{F}(x) = \left\{ \begin{array}{ll} 0 & \quad \text{si } x < 0 \\ 1 - p & \quad \text{si } 0 \leqslant x < 1 \\ 1 & \quad \text{si } x \geqslant 1 \end{array} \right.$$



- ▶ Let U an urn containing two white ball and three red balls.
- ▶ We randomly take one ball out of the box.
- ▶ Let A : "take one white ball out".
- ▶ Let X be the indicator random variable of A.

Find the probability distribution and the distribution function of X.



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The probability distribution of \boldsymbol{X} is

k	0	1
P(X=k)	35	$\frac{2}{5}$

and its distribution function is:

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Moments of a discrete random variable



Expected value

Definition

For a discrete random variable X with probability distribution p(.), we define the expected value of X, called E(X), by

$$E(X) = \sum_{i \in \mathbb{N}} x_i p(x_i)$$

Think about Means



Expected value

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$$\mathsf{E}(\mathsf{X}) = \sum_{i \in \mathbb{N}} \mathsf{x}_i \mathsf{p}(\mathsf{x}_i)$$

In concrete terms, the expected value of X is the weighted mean of the values of X, the weights being the probabilities associated to the values of X.



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In concrete terms, the expected value of X is the weighted mean of the values of X, the weights being the probabilities associated to the values of X.

Examples

1. In the previous example where we play three times to "heads or tails", the expected value of X is:

$$E(X) = \underbrace{0 \times \frac{1}{8}}_{8} + \underbrace{1 \times \frac{3}{8}}_{8} + \underbrace{2 \times \frac{3}{8}}_{8} + \underbrace{3 \times \frac{1}{8}}_{8} = \underbrace{1.5}_{1.5}$$

2. For the indicator random variable of A:

$$E(X) = 0 \times P(X = 0) + 1 \times P(X = 1) = P(A) = p$$

which means that the expected value of the indicator of an event A corresponds to the probability that A occurs.

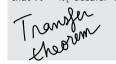


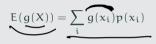


Expected value of a function of a random variable

Theorem

Let X be a discrete random variable whose possible values are x_i , $i \ge 1$, and denote by $p(x_i)$ the probability that $X = x_i$ occurs. Then, for any real function g, we have





 $E(\chi^2) = \sum \chi_i^2 P(\chi = \chi_i)$



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$$\mathsf{E}(\mathfrak{g}(X)) = \sum_{\mathfrak{i}} \mathfrak{g}(\mathfrak{x}_{\mathfrak{i}}) \mathfrak{p}(\mathfrak{x}_{\mathfrak{i}})$$

Example

Let X be a random variable that can take three values $\{-1, 0, 1\}$ with the following probabilities:

$$P(X = -1) = 0.2$$
 $P(X = 0) = 0.5$ $P(X = 1) = 0.3$

Calculate $E(X^2)$.



Solution



Solution

First method: Let $Y = X^2$.

Second method: Using the theorem



Solution

First method: Let $Y = X^2$. The probability distribution of Y is given by

$$P(Y = 1) = P(X = -1) + P(X = 1) = 0.5$$
$$P(Y = 0) = P(X = 0) = 0.5$$

So

 $\mathsf{E}(X^2) = \mathsf{E}(Y) = \mathbf{1}(0.5) + \mathbf{0}(0.5) = 0.5$

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So

$$E(X^2) = E(Y) = 1(0.5) + 0(0.5) = 0.5$$

Second method: Using the theorem

$$E(X^2) = (-1)^2(0.2) + 0^2(0.5) + 1^2(0.3)$$
$$= 1(0.2 + 0.3) + 0(0.5) = 0.5$$



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Remark

$$0.5 = E(X^2) \neq (E(X))^2 = 0.01$$



1. E(X + a) = E(X) + a, $a \in \mathbb{R}$



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results which follows from:

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2. $E(\alpha X) = \alpha E(X), \quad \alpha \in \mathbb{R}$



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to prove it, just write:

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3. E(X + Y) = E(X) + E(Y), X and Y being two random variables.



1. E(X + a) = E(X) + a, $a \in \mathbb{R}$

results which follows from:

$$\sum_{i} p_{i}(x_{i} + a) = \sum_{i} p_{i}x_{i} + \sum_{i} ap_{i} = \sum_{i} p_{i}x_{i} + a\sum_{i} p_{i} = \sum_{i} p_{i}x_{i} + a$$

2. $E(aX) = aE(X), \quad a \in \mathbb{R}$

to prove it, just write:

$$\sum_{i} p_{i} a x_{i} = a \sum_{i} p_{i} x_{i}$$

3. E(X + Y) = E(X) + E(Y), X and Y being two random variables.

All these three properties are summarised in the claim that the expected value is linear:

 $\mathsf{E}(\lambda X + \mu Y) = \lambda \mathsf{E}(X) + \mu \mathsf{E}(Y), \quad \forall \lambda \in \mathbb{R}, \, \forall \mu \in \mathbb{R}.$



Let X be a discrete random variable. We call variance of X, denoted V(X), the quantity defined by, when it exists,

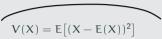
$$V(X) = E[(X - E(X))^2]$$

Thus, the variance is the expected value of the square of the centered random variable X - E(X). The variance can be interpreted as a measure of the dispersion of the possible values of X around its expected value.



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Indeed:

$$V(X) = E [X^2 - 2XE(X) + E^2(X)]$$

= E(X²) - E[2XE(X)] + E[E²(X)]
= E(X²) - 2E²(X) + E²(X)



Example

OLet us compute V(X) in the case where X is the number obtained when throwing a fair die.



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OLet us compute $V(\boldsymbol{X})$ in the case where \boldsymbol{X} is the number obtained when throwing a fair die.

Previously, we saw that $E(X) = \frac{7}{2}$. Moreover,

$$\begin{split} \mathsf{E}(\mathsf{X}^2) &= \sum_{i} x_i^2 \mathsf{p}(x_i) \\ &= 1^2 \left(\frac{1}{6}\right) + 2^2 \left(\frac{1}{6}\right) + 3^2 \left(\frac{1}{6}\right) + 4^2 \left(\frac{1}{6}\right) + 5^2 \left(\frac{1}{6}\right) + 6^2 \left(\frac{1}{6}\right) \\ &= \left(\frac{1}{6}\right) (91) = \frac{91}{6} \end{split}$$



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And therefore

$$V(X) = E(X^{2}) - E^{2}(X)$$
$$= \frac{91}{6} - \left(\frac{7}{2}\right)^{2} = \frac{35}{12}$$



Properties

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en effet:

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$$\sigma_{\rm X} = \sqrt{{\rm V}({\rm X})}$$



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- Expected value and standard deviation are linked through *Bienaymé-Tchebychev inequality*.



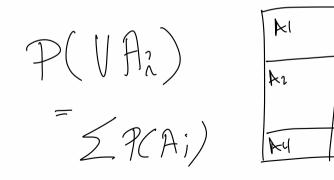


Theorem

Let X a random variable of expected value μ and variance $\sigma^2.$ For all $\epsilon>0,$ We have:

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This inequality can be written in a slightly different fashion. Let $k = \epsilon / \sigma$.

$$P\left(|X - E(X)| \ge k\sigma\right) \leqslant \frac{1}{k^2}$$



Theorem

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$$\mathsf{P}\left(|\mathsf{X} - \mathsf{E}(\mathsf{X})| \ge \varepsilon\right) \leqslant \frac{\sigma^2}{\varepsilon^2}$$

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$$P(|X - E(X)| \ge k\sigma) \le \frac{1}{k^2}$$

Importance

This inequality relates the probability for X to deviate from its expected value E(X) to its variance, which is precisely an indicator of the dispersion around the expected value. The inequality makes quantitatively precise the statement "the smaller the variance is, the less likely it is to find values far away from the expected value".



We call non centered moment of order $r\in\mathbb{N}^*$ of X the quantity, when it exists:

$$\mathfrak{m}_r(X) = \sum_{i \in \mathbb{N}} x_i^r p(x_i) = \mathsf{E}(X^r).$$



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Definition

The centered moment of order $r \in \mathbb{N}^*$ the quantity, when it exists:

$$\mu_{r}(X) = \sum_{i \in \mathbb{N}} p_{i} \left[x_{i} - E(X) \right]^{r} = E \left[X - E(X) \right]^{r}$$



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Remark

The first moments are:

•
$$\mathfrak{m}_1(X) = \mathsf{E}(X), \quad \mu_1(X) = 0.$$

•
$$\mu_2(X) = V(X) = m_2(X) - m_1^2(X).$$

Two Random Variables



So far, we have dealt with one random variable. However, it is often necessary to consider events related to two variables simultaneously, or even to more than two variables.



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Definition

Let X and Y two discrete random variables, defined on probability space $(\Omega, \mathcal{A}, \mathsf{P})$ and that $X(\Omega) = \{x_1, x_2, \ldots, x_l\} \text{ and } Y(\Omega) = \{y_1, y_2, \ldots, y_k\}, \ l \text{ and } k \in \mathbb{N}.$

The **probability law of** (X, Y) is defined by joint probabilities:

 $p_{ij} = P(X = x_i; Y = y_j) = P(\{X = x_i\} \cap \{Y = y_j\})$

We have

$$p_{ij} \ge 0$$
 et $\sum_{i=1}^{l} \sum_{j=1}^{k} p_{ij} = 1$

The pair (X, Y) is called two dimensional random vector and can have $l \times k$ valeurs.



The probabilities p_{ij} can be presented in a two dimensional table than we call joint probability distribution table:



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$X \setminus Y$	y1	y2	 yj	 y _k
χ_1	p ₁₁	p ₁₂	p_{1j}	p_{1k}
x ₂	p ₂₁	p ₂₂	p_{2j}	p_{2k}
:				
xi	P _{i1}	Pi2	Pij	p _{ik}
:	1	1 12	1 ()	1 110
:				
x_1	р 11	P12	Ρıj	pık

Table 1: Joint probability distribution table

In the header we have the possible values of Y and in the first column the possible values of X. The probability $p_{ij} = P(X = x_i; Y = y_j)$ is at the intersection of ith line and jth column.



Example

Three balls are drawn at random from an urn containing 3 red, 4 white and 5 black balls. X and Y are respectively the number of red and white balls drawn. Determine the joint probability distribution of the pair (X, Y).



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Solution

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- $|\Omega| = C_{12}^3 = 220.$
- $X(\Omega) = \{0, 1, 2, 3\}$ and $Y(\Omega) = \{0, 1, 2, 3\}$.



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- $p(X = 0, Y = 0) = p(0, 0) = C_5^3 / C_{12}^3 = \frac{10}{220}$.



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- ▶ $p(0,1) = C_4^1 C_5^2 / C_{12}^3 = \frac{40}{220}.$



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Table 2:	Joint	probability	distribution	table
----------	-------	-------------	--------------	-------

X\Y	0	1	2	3
0	$\frac{10}{220}$	$\frac{40}{220}$	$\frac{30}{220}$	$\frac{4}{220}$
1	$\frac{30}{220}$	$\frac{60}{220}$	$\frac{18}{220}$	0
2	$\frac{15}{220}$	$\frac{12}{220}$	0	0
3	$\frac{1}{220}$	0	0	0



When we know the joint distribution of the random variables X and Y, we can also look at the probability distribution of X alone and Y alone. These are the marginal probability distributions.



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► Marginal distribution of X:

$$p_{i.} = P(X = x_i) = P[\{X = x_i\} \cap \Omega] = \sum_{j=1}^k p_{ij} \quad \forall i = 1, 2, ..., l$$



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► Marginal distribution of Y:

$$p_{.j} = P(Y = y_j) = P[\Omega \cap \{Y = y_j\}] = \sum_{i=1}^{l} p_{ij} \quad \forall j = 1, 2, \dots, k$$

We can calculate the marginal distributions directly from the table of the joint distribution.



Table 3: Joint distribution table with marginal distributions

X\Y	y_1	y2	y _j	Уĸ	Marginal of X
x ₁	P11	p ₁₂	p _{1j}	\mathfrak{p}_{1k}	р 1.
x2	P21	P22	P _{2j}	\mathfrak{p}_{2k}	р _{2.}
:					
xi	p _{i1}	Pi2	Pij	p_{ik}	Pi.
xl	р 11	P ւ2	Pıj	p_{lk}	pι.
Marginal of Y	p.1	р. ₂	p.ı	p _{.k}	1



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Solution

Table 4: Joint distribution table

$X \setminus Y$	0	1	2	3	$p_{\mathfrak{i}.} = P(X = x_{\mathfrak{i}})$
0	$\frac{10}{220}$	<u>40</u> 220	$\frac{30}{220}$	$\frac{4}{220}$	$\frac{84}{220}$
1	$\frac{30}{220}$	$\frac{60}{220}$	$\frac{18}{220}$	0	$\frac{108}{220}$
2	$\frac{15}{220}$	$\frac{12}{220}$	0	0	<u>27</u> 220
3	$\frac{1}{220}$	0	0	0	$\frac{1}{220}$
$p_{.j} = P(Y = y_j)$	<u>56</u> 220	$\frac{112}{220}$	<u>48</u> 220	$\frac{4}{220}$	1



For each value y_j of Y such that $p_{,j}=P(Y=y_j)\neq 0$ we can define the conditional distribution of X given $Y=y_j$ by



Conditional Probability

Definition

For each value y_j of Y such that $p_{,j}=P(Y=y_j)\neq 0$ we can define the conditional distribution of X given $Y=y_j$ by

$$p_{i/j} = P(X = x_i/Y = y_j) = \frac{P(X = x_i; Y = y_j)}{P(Y = y_j)} = \frac{p_{ij}}{p_{,j}} \qquad \forall i = 1, 2, \dots, l$$



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Same for Y given $X = x_i$:

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We say that two random variables are independent iff

$$P(X = x_i; Y = y_j) = P(X = x_i)P(Y = y_j) \qquad \forall i = 1, 2, ..., l \text{ and } j = 1, 2, ..., k$$

One demonstrates that

 $P(\{X \in A\} \cap \{Y \in B\}) = P(\{X \in A\})P(\{Y \in B\}) \qquad \forall \ A \text{ and } B \in \mathcal{A}$



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Let two random variables X and Y,

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Properties

Let two random variables X and Y,

1. E(X + Y) = E(X) + E(Y)

2. If X and Y are independent so E(XY) = E(X)E(Y). But the reciprocal is not always true.



Definition

Let two random variables X and Y. The covariance of X and Y, when it exists, is

$$Cov(X,Y) = E[(X - E(X))(Y - E(Y))] = \sum_{i} \sum_{j} (x_{i} - E(X))(y_{j} - E(Y))p_{ij}$$

that we can calculate using the formula

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- V(X + Y) = V(X) + V(Y) + 2Cov(X, Y)
- \blacktriangleright If X and Y are independant so
 - Cov(X, Y) = 0 (the reciprocal is not always true)
 - V(X + Y) = V(X) + V(Y) (the reciprocal is not always true)



The correlation between X and Y is defined by

$$\rho = \rho(X,Y) = \frac{C \sigma \nu(X,Y)}{\sqrt{V(X)V(Y)}} = \frac{C \sigma \nu(X,Y)}{\sigma_X \sigma_Y}$$

We can demonstrate that

 $-1 \leqslant \rho(X,Y) \leqslant 1$



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We can demonstrate that

 $-1 \leqslant \rho(X,Y) \leqslant 1$

Interpretation of ρ

- ▶ The correlation coefficient is a measure of the degree of linearity between X and Y.
- > Values of rho close to 1 or -1 indicate an almost rigorous linearity between X and Y.
- ▶ Values of rho close to 0 indicate the absence of any linear relationship.
- ▶ When $\rho(X, Y)$ is positive, Y tends to increase if X does the same.
- ▶ When $\rho(X, Y) < 0$, Y tends to decrease if X increases.



Linear correlation

